		1. Course Informa	ation	
1.1	Course Name:	Computer Vision	1.2: Course Code:	CS570
1.3	Credit Hours:	3	1.4: Contact Hours:	3
1.5	Pre- requisites:	Probability & Statistics, Linear Algebra		
1.6	information ex look into why well-founded "see". It is an	s (and even animals) "look" at the real-vextremely efficiently. Computers can fail "vision" is a difficult problem to solve at techniques used to solve the vision problem to solphysics inter-disciplinary area covering physics	catastrophically at this task! In this c nd we go through successful, mather olem. Computer vision tries to make o	ourse we natically computer nputer
		that can interpret the world around the		und 10
1.7	Course Outli Foundations of Lenses, Came Generalization Blur Filters, Im Pyramids; New and Robust Lenges and Generalization Metrology, Lenges and Generalization Blur Filters, Im Pyramids; New and Robust Lenges and Generalization Blur Filters, Im Pyramids; New and Robust Lenges and Generalization Blur Filters, Images and Gene	that can interpret the world around the	Computer Vision and Society; Image I ons of Learning, Gradient-Based Learn ge processing; Image Filtering, Linear ale Image Representations, Filter Ban hal Neural Networks, Transformers, Da on; Understanding Geometry, Representation, Stereo Vision, Homographies, S Image, Multiview Geometry and Stru-	Formation ing, Filters, ks, Image ataset Bia enting ingle Vie

	2. Unit-wise Major Topics 2.2						
Unit No	Topic Course Outline divided into topics	Teachi Hour					
U1	Foundations of Computer Vision			3			
U2	Image Formation						
U3	Foundations of Learning	4.5					
U4	Foundations of Image processing						
U5	Linear Filters						
U6	Sampling and Multiscale Image Representations	4.5					
U7	Neural Architectures for Vision	7.5					
U8	Understanding Geometry	10.5	;				
U9	Understanding Motion	3					
U10	Object Recognition	3					
Total Teaching Hours:				45			
CLO	Taxonomy, and (c) Program Level Out 3.2	comes (PL 2.1	Os). 3.3	3	3.4		
No		Unit No.	it No. Bloom's Taxonomy		LOs		
	3.1.1 CLOs for Theory			·			
		U1, U2	C2 (Understa	nd) 2-	-5, 9		
		U3, U7, U10	C2 (Understa	nd) 2	2-5		
		U4, U5, U6	C2 (Understa	nd) 2	2-5		
CLO-4	Understanding single and multi-view geomtery	U8	C2 (Understa	nd) 2	2-5		
CLO-5	Understanding motion	U9	C2 (Understa	nd) 2	2-5		
CLO-6		U3 - U10	C3 (Apply)	3	3-7		
			+				
	U1	U1 Foundations of Computer Vision U2 Image Formation U3 Foundations of Learning U4 Foundations of Image processing U5 Linear Filters U6 Sampling and Multiscale Image Representations U7 Neural Architectures for Vision U8 Understanding Geometry U9 Understanding Motion U10 Object Recognition  Mapping of each Course Learning Outcomes (CLOs Taxonomy, and (c) Program Level Outcomes CLO No. Description  3.2  Course Learning Outcomes (CLOs) Description  3.1.1 CLOs for Theory  CLO-1 Understanding the foundations of image formation, image perception and computer vision Understanding the foundations of machine learning for computer vision Understanding the fundamentals of image processing CLO-4 Understanding single and multi-view geomtery CLO-5 Understanding motion Apply concepts of CV for solving real world	Topic Course Outline divided into topics  U1 Foundations of Computer Vision  U2 Image Formation  U3 Foundations of Learning  U4 Foundations of Image processing  U5 Linear Filters  U6 Sampling and Multiscale Image Representations  U7 Neural Architectures for Vision  U8 Understanding Geometry  U9 Understanding Motion  U10 Object Recognition  Total Teach  Mapping of each Course Learning Outcomes (CLOs) to (a) Untraxonomy, and (c) Program Level Outcomes (PLOs)  Ocurse Learning Outcomes (CLOs)  Description  3.1.1 CLOs for Theory  CLO-1 Understanding the foundations of image formation, image perception and computer vision  CLO-2 Understanding the foundations of machine learning for computer vision  CLO-3 Understanding the fundamentals of image U4, U5, processing  CLO-4 Understanding single and multi-view geomtery  CLO-5 Understanding motion  U2 U13 L110	Topic Course Outline divided into topics  U1 Foundations of Computer Vision  U2 Image Formation  U3 Foundations of Learning  U4 Foundations of Image processing  U5 Linear Filters  U6 Sampling and Multiscale Image Representations  U7 Neural Architectures for Vision  U8 Understanding Geometry  U9 Understanding Motion  U10 Object Recognition  Total Teaching Hours:  Mapping of each Course Learning Outcomes (CLOs) to (a) Unit Nos., (b) Taxonomy, and (c) Program Level Outcomes (PLOs).  CLO No.  CLO No.  CLO Description  3.1.1 CLOs for Theory  CLO-1 Understanding the foundations of image formation, image perception and computer vision  CLO-2 Understanding the foundations of machine learning for computer vision  CLO-3 Understanding the fundamentals of image processing  CLO-4 Understanding single and multi-view geomtery  CLO-5 Understanding motion  U10 C2 (Understanding U9) C3 (Apply)	Topic Course Outline divided into topics    Hour   Foundations of Computer Vision   3   3   3   3   3   3   3   3   3		

			4. CLO Ass	essment l	Mechanism				
			3.1.1 CLOs for Theory						
		3.1.1.1	3.1.1.2	3.1.1.3	3.1.1.4	3.1.1.5	3.1.1.6		
4.1	Assessme Tools	nt CLO-1	CLO-2	CLO-3	CLO-4	CLO-5	CLO-6		
4.1.1	Quiz	Quiz 1	Quiz 2, 4	Quiz 3	Quiz 5, 6				
4.1.2	Assignmei / H.W.	nt	Assign. 1, 3	Assign. 2	Assign. 4, 5		Assign. 1-5		
4.1.3	Project								
4.1.4	Mid-term	Mid-Term	Mid-Term	Mid-Term					
4.1.4	Exam	Exam	Exam	Exam					
4.1.5	Final-term Exam		Final-term Exam						
			5. Re	ading Ma	terial				
5.1	Textbook:  1. Foundations of Computer Vision, Antonio Torralba, Philip Isola, William T. Freeman MIT Press, 2024						iam T. Freeman,		
5.2	Reference Books:	University 2. Multiple	<ol> <li>Computer Vision: Algorithms and Applications, 2nd Edition, Richard Szeliski, The University of Washington, 2022</li> <li>Multiple View Geometry in Computer Vision, by Richard Hartley and Andrew Zisserman.</li> </ol>						
			3. Digital Image Processing, $4^{\text{th}}$ Edition, Rafael Gonzalez and Richard Woods, Pearson, 2018.						
			6 1 2	cture-wise	Plan				
6.1	2.1		6.2			6.3	6.4		
Lecture	Unit No.	Topics Cover	opics Covered		Reading Quiz/Assi Material /Project				
No.					7770				
1.	U1	Introduction				Torralba Ch 1			
2.	U1	Looking at Im			and Society	Torralba Ch 3, 4			
3.	U2	Image format				Torralba Ch 5, 6			
4.	U2	Cameras as L	inear Systems	+ Color		Torralba Ch 7, 8	Quiz 1		

5.	U3	Introduction to Machine Learning	Torralba Ch 9	
6.	U3	Gradient-Based Learning + Generalization	Torralba Ch 10, 11	
7.	U3	Neural Networks	Torralba Ch 12, 13	
8.	U4	Linear Image Filtering	Torralba Ch 15	Quiz 2
9.	U4	Fourier Analysis	Torralba Ch 16	Assignment 1
10.	U5	Blur Filters	Torralba Ch 17	
11.	U5	Image Derivatives	Torralba Ch 18	
12.	U6	Image Sampling	Torralba Ch 20, 21	Quiz 3
13.	U6	Filter Banks	Torralba Ch 22	
14.	U6	Image Pyramids	Torralba Ch 23	Assignment 2
15.	U7	Convolutional Neural Networks	Torralba Ch 24	
16.	U7	Transformers	Torralba Ch 26	
17.		Mid-term Exam		
18.				
19.	U7	Perceptual Grouping	Torralba Ch 31	
20.	U7	Dataset Bias and Robust Learning	Torralba Ch 35, 36	
21.	U7	Transfer Learning and Adaptation	Torralba Ch 37	Assignment 3
22.	U8	Representing Images and Geometry	Torralba Ch 38	Quiz 4
23.	U8	Camera Modelling and Calibration	Torralba Ch 39	
24.	U8	Stereo Vision	Torralba Ch 40	
25.	U8	Homographies	Torralba Ch 41	Assignment 4
26.	U8	Single View Metrology	Torralba Ch 42	Quiz 5
27.	U8	Learning to Estimate Depth from a Single Image	Torralba Ch 43	
28.	U8	Multiview Geometry and Structure from Motion	Torralba Ch 44	Assignment 5
29.	U9	Motion Estimation	Torralba Ch 46, 47	Quiz 6
30.	U9	Optic Flow	Torralba Ch 48, 49	
31.	U10	Object Recognition	Torralba Ch 50	
32.		Conclusion		
		Final-term Exam		