- 1. (1 point) Convolutional layers are primarily used in neural networks to:
  - A. Reduce the size of the dataset
  - B. Extract spatial features from input data
  - C. Perform gradient descent optimization
  - D. Add non-linearity to the model
- 2. (1 point) Which activation function is most commonly used in convolutional neural networks?
  - A. Sigmoid
  - B. Tanh
  - C. ReLU (Rectified Linear Unit)
  - D. Softmax
- 3. (1 point) What is the purpose of padding in convolutional layers?
  - A. To reduce the number of parameters
  - B. To preserve spatial dimensions after convolution
  - C. To increase the depth of the feature map
  - D. To normalize feature values
- 4. (1 point) Which of the following is an advantage of using CNNs for image classification?
  - A. They are invariant to spatial transformations
  - B. They reduce computational complexity
  - C. Both of the above
  - D. None of the above
- 5. (1 point) What does a kernel in a convolutional layer represent?
  - A. The entire set of weights in the network
  - B. A small matrix used to extract specific features
  - C. The function used for backpropagation
  - D. The bias added to the layer
- 6. (1 point) True or False: In CNNs, pooling layers are used to reduce the spatial dimensions of feature maps. **A. True** B. False
- 7. (1 point) True or False: Convolution operations in CNNs are linear transformations. **A. True**B. False
- 8. (1 point) True or False: Max-pooling selects the maximum value from a region of the feature map. A. True B. False
- 9. (1 point) True or False: Strided convolution increases the resolution of the output feature map. A. True B. False
- 10. (1 point) True or False: Fully connected layers are typically used at the end of a CNN to make predictions. **A. True** B. False