

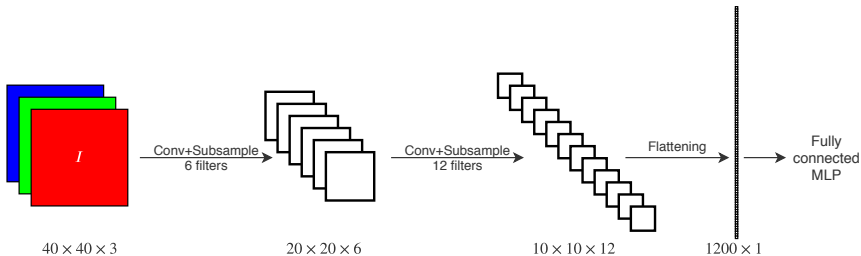
# CS-568 Deep Learning

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PUCIT

Backpropagation in a CNN

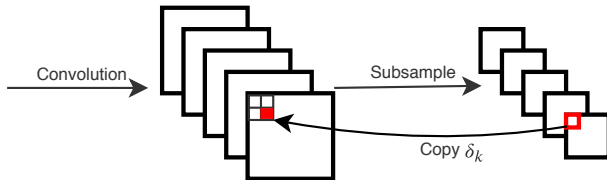
# Backpropagation in CNNs



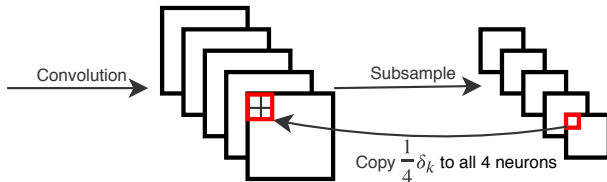
1. Compute  $\delta_k = \frac{\partial L}{\partial a_k}$  for each neuron in flattened layer using standard MLP backpropagation.
2. *Directly copy* these  $\delta_k$ s at corresponding locations of previous subsampling layer.

## Backpropagation from subsampling to convolution layer

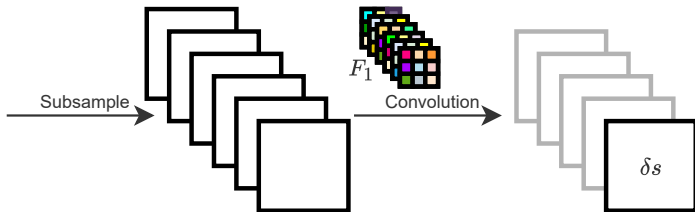
- ▶ Record index of pooled neuron during forward pass.
- ▶ Backpropagate  $\delta$  only to this pooled neuron.



- ▶ Mean-pooling is different.
  - ▶ All neurons are picked with uniform weight in forward pass.
  - ▶ So backpropagate  $\delta$  to each neuron with uniform weight.



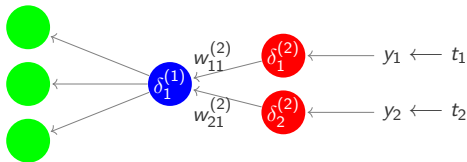
# Backpropagation in a convolutional layer



## Backpropagation Equation

Recall the backpropagation equation for a traditional neuron.

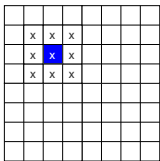
$$\delta_j^{(1)} = h'(a_j) \sum_{k=1}^K \delta_k^{(2)} w_{kj}$$



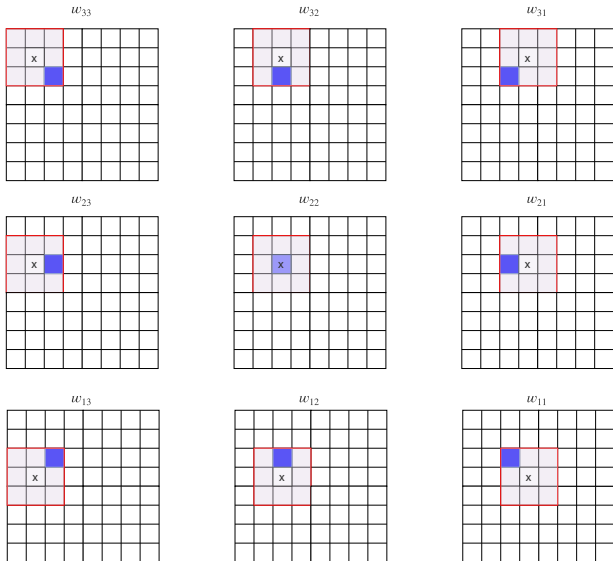
1. Take all neurons *affected* by neuron  $j$ .
2. Compute dot-product between **their  $\delta$  values** and connecting weights.
3. Multiply result by derivative of activation function of neuron  $j$ .

# Backpropagation in a convolutional layer

- ▶ Consider a neuron in a convolutional layer.
- ▶ In the forward pass, the blue neuron affects all neurons marked by x in the next layer.



- ▶ *Notice the flipped role of weights.*



## Backpropagation in a convolutional layer

- In the backward pass, the blue neuron computes the dot-product between  $\delta$  values at the  $x$ -locations and connecting weights.

	x	x	x				
	x	x	x				
	x	x	x				

$\delta_{11}$							
	$\delta_{22}$	$\delta_{23}$	$\delta_{24}$				
	$\delta_{32}$	$\delta_{33}$	$\delta_{34}$				
	$\delta_{42}$	$\delta_{43}$	$\delta_{44}$				
							$\delta_{88}$

	$w_{33}$	$w_{32}$	$w_{31}$				
	$w_{23}$	$w_{22}$	$w_{21}$				
	$w_{13}$	$w_{12}$	$w_{11}$				

- The connecting weights are a horizontally and vertically flipped version of the weights used in the forward convolution pass.

## Backpropagation in a convolutional layer

- ▶ The adjacent red neuron affects a new but overlapping set of  $x$ -locations *using the same connecting weights*.

		x	x	x			
		x	x	x			
		x	x	x			

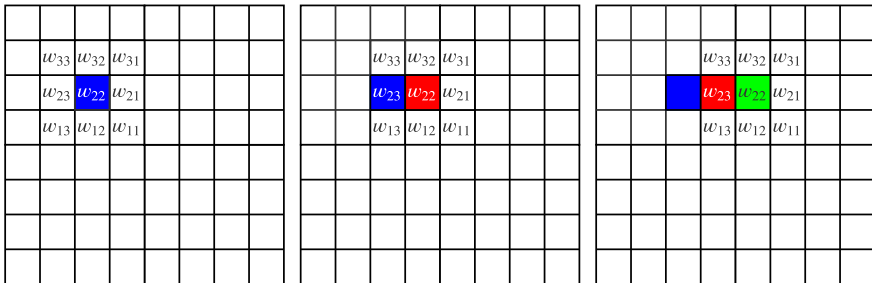
$\delta_{11}$							
		$\delta_{23}$	$\delta_{24}$	$\delta_{25}$			
		$\delta_{33}$	$\delta_{34}$	$\delta_{35}$			
		$\delta_{43}$	$\delta_{44}$	$\delta_{45}$			
							$\delta_{88}$

		$w_{33}$	$w_{32}$	$w_{31}$			
		$w_{23}$	$w_{22}$	$w_{21}$			
		$w_{13}$	$w_{12}$	$w_{11}$			

- ▶ *Since the weights are shared*, the only difference is between the  $x$ -locations.



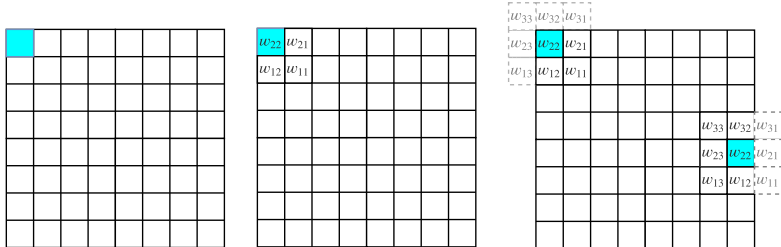
## Backpropagation in a convolutional layer



- ▶ Equivalent to convolving the  $\delta$ -map by flipped weights.
- ▶ Therefore, backpropagation of  $\delta$  values from a convolution layer is
  1. *just a convolution of the  $\delta$ -map using flipped weights,*
  2. followed by multiplication with derivatives of activation functions.

## Backpropagation in a convolutional layer

- ▶ What about boundary neurons? Who did they affect?



- ▶ Equivalent to convolving the  $\delta$ -map by flipped weights *using zero-padding*.
- ▶ Therefore, backpropagation of  $\delta$  values from a convolution layer is
  1. *just a convolution of the  $\delta$ -map using flipped weights with zero-padding*,
  2. followed by multiplication with derivatives of activation functions.

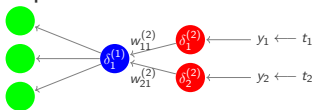
## Computing gradients in convolutional layer

- ▶ Consider a *valid* convolution of an  $n \times n$  array with another  $n \times n$  array.
  - ▶ *Size* of the result will be  $1 \times 1$ .
- ▶ Now consider a *valid* convolution of an  $(n + 1) \times (n + 1)$  array with an  $n \times n$  array.
  - ▶ What will be the *size* of the result?
- ▶ Now consider a *valid* convolution of an  $(n + 2) \times (n + 2)$  array with an  $n \times n$  array.
  - ▶ What will be the *size* of the result?

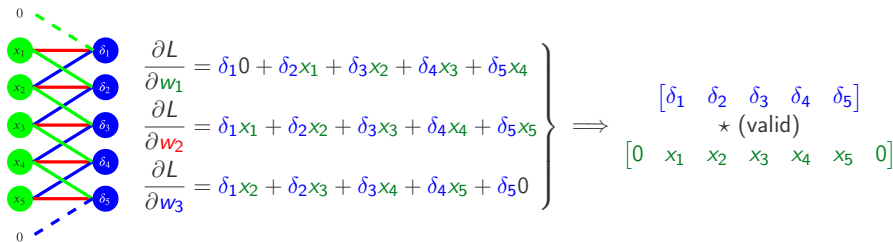
# Computing gradients in convolutional layer

1D case

- ▶ Backpropagation computes the per-neuron  $\delta$ -maps only.
- ▶ Per-weight derivatives are computed as the product of a *traditional* neuron's  $\delta$  value and its input.



- ▶ Consider 1D convolutional layer with  $3 \times 1$  filter.

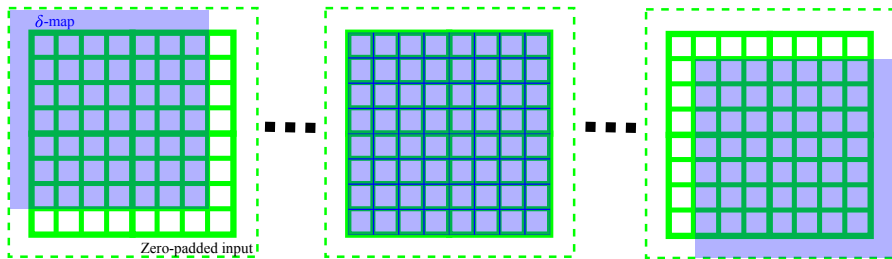


- ▶ Verify that  $\frac{\partial L}{\partial b} = \sum \delta_i$ .

# Computing gradients in convolutional layer

2D case

1. Zero-pad the input array with  $\lfloor \frac{K}{2} \rfloor$  zeros on each side<sup>1</sup>.
2. Perform *valid* convolution of the *zero-padded input array* by the  $\delta$ -map of the next layer to obtain a  $K \times K$  array of derivatives of the convolution weights.



3. Derivative of bias is just the sum of the  $\delta$ -map.

<sup>1</sup>Assuming square  $K \times K$  convolution filter where  $K$  is odd

## Summary

- ▶ From FC to Subsampling:  
Direct copying of  $\delta$ -values.
- ▶ From Subsampling to Conv:  
Direct copy or weighted combination of  $\delta$ -map.
- ▶ From Conv:  
`conv2d(zeropad( $\delta$ -map), fliplr(flipud(F)), 'valid')`
- ▶ Gradients of convolution filter F:  
`conv2d(zeropad(input array),  $\delta$ -map, 'valid')`
- ▶ Gradient of bias:  
sum of  $\delta$ -map