CS-667 Advanced Machine Learning

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Conditional Mixture Models

Combining Models

- So far, we have seen how to model complicated machine learning problems by combining simpler models.
 - Boosting for learning a strong classifier by sequentially learning weak classifiers.
 - Gaussian mixture models for modelling (unconditional) density $p(\mathbf{x})$.
- ▶ In this lecture, we will model conditional density p(t|x) by combining simpler models
 - For continuous t, we obtain a mixture of linear regression models.
 - For discrete t, we obtain a mixture of logistic regression models.
- As before, parameter learning for mixture models will be achieved by the EM algorithm.

Linear Regression Recap

- We have already covered the probabilistic perspective of linear regression in our polynomial fitting example.
- ▶ We assumed that target t was given by a deterministic function y(x, w) with additive Gaussian noise. That is

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon$$

where $\epsilon \sim \mathcal{N}(0, \beta^{-1})$.

▶ Therefore, we wrote the conditional density of the target as

$$p(t|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t|y(\mathbf{x}, \mathbf{w}), \beta^{-1})$$

Linear Regression Recap

Likelihood for i.i.d data $\{(x_1, t_1), \dots, (x_N, t_N)\}$ can be written as

$$\prod_{n=1}^{N} \mathcal{N}(t_n | \mathbf{w}^T \phi(\mathbf{x}_n), \beta^{-1})$$

Log-likelihood becomes

$$\frac{N}{2}\ln\beta - \frac{N}{2}\ln(2\pi) - \beta \underbrace{\frac{1}{2}\sum_{n=1}^{N}\{t_n - \mathbf{w}^T\phi(\mathbf{x_n})\}^2}_{\text{SSE}}$$

► Therefore, maximisation of log-likelihood with respect to w is equivalent to minimisation of SSE function.

Linear Regression Recap

- ▶ Gradient with respect to **w** is $\sum_{n=1}^{N} \{t_n \mathbf{w}^T \phi(\mathbf{x_n})\} \phi(\mathbf{x_n})^T$.
- Equating gradient to the 0 vector

$$0 = \sum_{n=1}^{N} t_n \phi(\mathsf{x_n})^T - \mathsf{w}_{\mathsf{ML}}^T \left(\sum_{n=1}^{N} \phi(\mathsf{x_n}) \phi(\mathsf{x_n})^T \right)$$

 By converting to a pure matrix-vector notation, we found the maximum-likelihood solution for linear regression as

$$\mathsf{w}_\mathsf{ML} = \underbrace{(\Phi^\mathsf{T}\Phi)^{-1}\Phi^\mathsf{T}}_{\Phi^\dagger}\mathsf{t}$$

where Φ denoted the design matrix and t denoted the vector of all N target values.

EM Algorithm Recap

Goal is to maximise likelihood $p(X|\theta)$ with respect to θ by introducing joint distribution $p(X,Z|\theta)$ involving latent variables Z.

- 1. Choose initial θ^{old}
- 2. E-step: Evaluate $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$
- 3. M-step: Obtain new estimate θ^{new} by maximising the expectation $\mathcal{Q}(\theta, \theta^{\text{old}})$

$$\theta^{\mathsf{new}} = \arg\max_{\theta} \mathcal{Q}(\theta, \theta^{\mathsf{old}})$$

where
$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \ln p(\mathbf{X}, \mathbf{Z}|\theta)$$
.

4. Check for convergence of either log-likelihood or parameters. If not converged, then

$$\boldsymbol{\theta}^{\mathsf{old}} \leftarrow \boldsymbol{\theta}^{\mathsf{new}}$$

and return to step 2.

- Fitting a single linear function to data being generated from multiple sources gives very poor results.
- ▶ Instead of a single Gaussian, we now model the conditional density of targets t_n by a mixture of K Gaussians

$$p(t_n|\mathbf{x}_n, \boldsymbol{\theta}) = \sum_{k=1}^K \pi_k \mathcal{N}_k(t_n|y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1})$$

where \mathbf{w}_k are the parameters of the linear function representing the mean of the k-th Gaussian component and β_k^{-1} is the precision of that component.

Notice that this is a mixture of *conditional* Gaussians $p(t|\mathbf{x})$ and therefore different from the standard Gaussian Mixture Model which uses marginal densities p(x).

 \triangleright For i.i.d data (X,t), log-likelihood can therefore be written as

$$\ln p(\mathbf{t}|\mathbf{X}, \boldsymbol{\theta}) = \ln \left(\prod_{n=1}^{N} p(t_n|\mathbf{x}_n, \boldsymbol{\theta}) \right)$$
$$= \sum_{n=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \mathcal{N}_k(t_n|y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1}) \right)$$

where the summation over k 'blocks'the natural logarithm from acting on the exponential function.

- As in the case of GMMs, we maximise log-likelihood by the EM algorithm.
- ► For that we need to view the problem in terms of latent variables.

- Let $z_{nk} = 1$ imply that training data point n was generated by the k-th source (model component).
- ▶ Then for every observed t_n there is a corresponding K-dimensional vector \mathbf{z}_n with 1-of-K coding.
- Since we do not know how the data was generated, the z_n are unobserved/hidden/latent variables.

 Log-likelihood for complete data (observed + unobserved) can be written as

$$\ln p(\mathbf{t}, \mathbf{Z}|\mathbf{X}, \boldsymbol{\theta}) = \ln \left(\prod_{n=1}^{N} p(t_n, \mathbf{z}_n | \mathbf{x}_n, \boldsymbol{\theta}) \right)$$

$$= \ln \left(\prod_{n=1}^{N} \prod_{k=1}^{K} \{ \pi_k \mathcal{N}_k(t_n | y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1}) \}^{z_{nk}} \right)$$

$$= \sum_{n=1}^{N} \sum_{k=1}^{K} z_{nk} \ln \left(\pi_k \mathcal{N}_k(t_n | y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1}) \right)$$

which is not computable since we do not know the values of the latent variables \mathbf{Z} .

▶ However, expected log-likelihood for complete data is computable if model parameters θ are known. This is the *E-step*.

$$\begin{split} \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) &= \mathbb{E}_{\mathbf{Z}|\mathbf{t}}[\ln p(\mathbf{t}, \mathbf{Z}|\mathbf{X}, \boldsymbol{\theta})] \\ &= \sum_{n=1}^{N} \sum_{\mathbf{z}_{n}} \sum_{k=1}^{K} p(z_{nk}|t_{n}) z_{nk} \ln \left(\pi_{k} \mathcal{N}_{k}(t_{n}|y(\mathbf{x}_{n}, \mathbf{w}_{k}), \beta_{k}^{-1}) \right) \\ &= \sum_{n=1}^{N} \sum_{k=1}^{K} \underbrace{p(z_{nk} = 1|t_{n})}_{r_{nk}} \ln \left(\pi_{k} \mathcal{N}_{k}(t_{n}|y(\mathbf{x}_{n}, \mathbf{w}_{k}), \beta_{k}^{-1}) \right) \end{split}$$

where responsibilities r_{nk} are computed using Bayes' theorem

$$r_{nk} = \frac{p(z_{nk} = 1)p(t_n|z_{nk} = 1)}{\sum_{j=1}^{K} p(z_{nj} = 1)p(t_n|z_{nj} = 1)} = \frac{\pi_k \mathcal{N}_k(t_n|y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1})}{\sum_{j=1}^{K} \pi_j \mathcal{N}_j(t_n|y(\mathbf{x}_n, \mathbf{w}_j), \beta_j^{-1})}$$

- ▶ In the *M-step*, we fix the responsibilities and update the parameters $\theta = \{\pi_k, \mathbf{w}_k, \beta_k\}$.
- ightharpoonup Since the mixing coefficients π_k represent probabilities, they are optimised for via Lagrange multipliers to yield

$$\pi_k^* = \frac{N_k}{N} = \frac{\sum_{n=1}^N r_{nk}}{N}$$

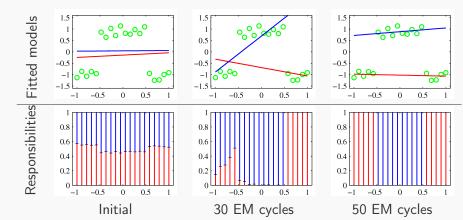
ightharpoonup Optimal regression weights \mathbf{w}_k are obtained as the solution to a weighted least-squares problem

$$\mathbf{w}_k^* = \left(\mathbf{\Phi}^T \mathsf{R}_k \mathbf{\Phi}\right)^{-1} \mathbf{\Phi}^T \mathsf{R}_k \mathbf{t}$$

where $R_k = \text{diag}(r_{nk})$ is an $N \times N$ diagonal matrix of weights that is recomputed at each E-step.

▶ Finally, optimal precision β_k is obtained as

$$\frac{1}{\beta_k^*} = \frac{\sum_{n=1}^N r_{nk} (t_n - \mathbf{w}_k^{*T} \phi_n)^2}{\sum_{n=1}^N r_{nk}} = \frac{1}{N_k} \sum_{n=1}^N r_{nk} (t_n - \mathbf{w}_k^{*T} \phi_n)^2$$



EM Algorithm for Mixutre of Linear Regression Models

Data: Data points $\{(\mathbf{x}_1, t_1), \dots, (\mathbf{x}_N, t_N)\}$, integer K > 1.

Result: Component parameters $\{\mathbf{w}_k, \beta_k\}$, mixing coefficients $\{\pi_k\}$

- 1. Choose some initial values for $\mathbf{w}_k, \beta_k, \pi_k$
- 2. Fix parameters, update responsibilities

$$r_{nk} = \frac{\pi_k \mathcal{N}_k(t_n | y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1})}{\sum_{j=1}^K \pi_j \mathcal{N}_j(t_n | y(\mathbf{x}_n, \mathbf{w}_j), \beta_j^{-1})}$$

3. Fix responsibilities, update parameters

$$\pi_k = \frac{N_k}{N}$$

$$\mathbf{w}_k = \left(\mathbf{\Phi}^T \mathbf{R}_k \mathbf{\Phi}\right)^{-1} \mathbf{\Phi}^T \mathbf{R}_k \mathbf{t}$$

$$\beta_k = \frac{N_k}{\sum_{n=1}^{N} r_{nk} (t_n - \mathbf{w}_k^T \phi_n)^2}$$

where $N_k = \sum_{n=1}^{N} r_{nk}$ and $R_k = \text{diag}(r_{nk})$.

EM Algorithm for Mixutre of Linear Regression Models

4. Evaluate log-likelihood

$$\ln p(\mathbf{t}|\mathbf{X}, \boldsymbol{\theta}) = \sum_{n=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \mathcal{N}_k(t_n | y(\mathbf{x}_n, \mathbf{w}_k), \beta_k^{-1}) \right)$$

and check for convergence of either log-likelihood or parameters. If not converged, return to step 2.

- For binary classification problems, we studied logistic regression which outputs posterior probabilities p(t|x) for $t = \{0, 1\}$.
- This allows us to use logistic regression as a component of more complicated probabilistic models.
- A mixture of K logistic regression models can be constructed as

$$p(t|\phi,\theta) = \sum_{k=1}^K \pi_k y_k^t (1-y_k)^{1-t}$$

where $y_k = \sigma(\mathbf{w}_k^T \phi)$ is the output of component k and the adjustable parameters are $\theta = \{\pi_k, \mathbf{w}_k\}$.

► Can be extended to multiclass problems as *mixture of softmax models*.

▶ Given i.i.d. data $\{\phi_n, t_n\}$, incomplete data log-likelihood can be written as

$$p(\mathbf{t}|\theta) = \prod_{n=1}^{N} \sum_{k=1}^{K} \pi_k y_{nk}^{t_n} (1 - y_{nk})^{1 - t_n}$$

where $y_{nk} = \sigma(\mathbf{w}_k^T \phi_n)$.

▶ By employing latent variables z_{nk} with 1-of-K coding, we can write the *complete data likelihood* as

$$p(\mathbf{t}, \mathbf{z}|\boldsymbol{\theta}) = \prod_{n=1}^{N} \prod_{k=1}^{K} \{\pi_k y_{nk}^{t_n} (1 - y_{nk})^{1 - t_n}\}^{z_{nk}}$$

and then use EM for parameter learning.

► E-step: Compute responsibilities

$$r_{nk} = p(z_{nk} = 1|t_n)$$

$$= \frac{p(z_{nk} = 1)p(t_n|z_{nk} = 1)}{\sum_{j=1}^{K} p(z_{nj} = 1)p(t_n|z_{nj} = 1)} = \frac{\pi_k y_{nk}^{t_n} (1 - y_{nk})^{1 - t_n}}{\sum_{j=1}^{K} \pi_j y_{nj}^{t_n} (1 - y_{nj})^{1 - t_n}}$$

Allows us to write the expected complete data log-likelihood

$$\begin{aligned} \mathcal{Q}(\theta, \theta^{\text{old}}) &= \mathbb{E}_{\mathbf{Z}|\mathbf{t}}[\ln p(\mathbf{t}, \mathbf{Z}|\mathbf{X}, \theta)] \\ &= \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} \{\ln \pi_k + t_n \ln y_{nk} + (1 - t_n) \ln(1 - y_{nk})\} \end{aligned}$$

▶ M-step: Maximise $Q(\theta, \theta^{\text{old}})$ with respect to π_k via Lagrange multipliers to obtain

$$\pi_k^* = \frac{N_k}{N} = \frac{\sum_{n=1}^N r_{nk}}{N}$$

▶ Find optimal classifier weights \mathbf{w}_k^* via IRLS which requires computation of the gradient vector

$$\nabla_{\mathbf{w}_k} \mathcal{Q} = \sum_{n=1}^N r_{nk} (t_n - y_{nk}) \phi_n$$

and the Hessian matrix

$$\nabla_{\mathbf{w}_k} \nabla_{\mathbf{w}_k} \mathcal{Q} = -\sum_{n=1}^N r_{nk} y_{nk} (1 - y_{nk}) \phi_n \phi_n^T$$

Mixture of Experts

▶ By allowing the mixing coefficients to depend on the input, we can obtain an even more powerful class of mixture models.

$$p(t|\mathbf{x}, \boldsymbol{\theta}) = \sum_{k=1}^{K} \pi_k(\mathbf{x}) p_k(t|\mathbf{x}, \boldsymbol{\theta})$$

- ▶ The input-dependent mixing coefficients $\pi_k(x)$ are known as gating functions.
- ▶ The individual component densities $p_k(t|\mathbf{x}, \boldsymbol{\theta})$ are known as the *experts*.
- ▶ Gating functions $\pi_k(x)$ determine which model is how much of an expert in which region of input space.

Mixture of Experts

One choice of gating functions is the linear softmax

$$\pi_k(\mathbf{x}) = \frac{e^{\mathbf{v}_k^T \mathbf{x}}}{\sum_{j=1}^K e^{\mathbf{v}_j^T \mathbf{x}}}$$

- ▶ Parameters θ now include the linear softmax weights $\{v_k\}$.
- If the experts are also linear, learning can be performed using the EM algorithm.